

Development and validation of a bicycle helmet: Assessment of head injury risk under standard impact conditions

G. Milne¹, C. Deck¹, N. Bourdet¹, R.P. Carreira², Q. Allinne², R. Willinger¹

Abstract Although cycling may be attractive for both economic and environmental reasons, cyclists are extremely vulnerable road users and subjected to falls or collisions with cars. This present research attempts to understand the degree of protection offered by a commercial bicycle helmet under standard impact conditions. In accordance with the EN 1078 standard, an experimental program has been carried out on an existing helmet by performing 90 normative impacts under three different types of conditionings. In parallel, this helmet has been digitalized and meshed to get a finite element model (FEM) that has been implemented under the LS-DYNA[®] crash code. The experimental tests have been numerically reproduced in order to provide an in-depth validation of the helmet model under each of the 90 experimental impacts. The bicycle helmet model was finally coupled to a detailed human head model in order to compute intra-cranial field parameters and to assess the head injury risk. Results show that the calculated intra-cranial parameters were higher than previously published human head tolerance limits in terms of diffuse axonal injuries (DAI) and subdural hematoma (SDH) illustrating thus the critical level of loading under standard helmet test conditions.

ρ	Specific mass (kg/m ³)
E	Young's modulus (MPa)
$E_{unloading}$	Unloading modulus (MPa)
ν	Poisson's coefficient (-)

Keywords: *Bicycle helmet, Helmet modeling, Head modeling, Head injuries, Standards*

I. INTRODUCTION

Cycling represents one of the most popular recreational sports, but also one of the main transportation means all over the world and more specifically in urban areas. As reported by the United Nations in 2003 [1], road traffic injuries caused the death of more than one million humans in year 2000, representing the ninth highest cause of death worldwide. Many previous studies have outlined the effectiveness of wearing bicycle helmets [2]-[3] and also the possibility of the improvement of currently used helmet design [4]-[5]. According to Belgian statistics published in a recent survey [6], 9.6% of the study subjects in 1999 took a ride on their bikes. From this percentage, 7.3% used the bike as their main method of transportation to work and 19.2% to school. In 2000, a total of 6655 injuries and 134 fatalities were attributed to cycling accidents in Belgium on public roads. 9.8% of all road accidents and 9.1% of road traffic deaths were represented by pedal cyclists.

The head represents the most vulnerable part of the human body and one of the most important to be protected. Between 21-61% of the victims of bicycle accidents seeking medical care have a head injury as reported by Collins *et al.* in 1993 [7] and Eilert-Petersson & Schelp in 1997 [8]. The medical care required by this large number of victims also implies high costs both economical and societal. Bicycling dramatically leads to increased numbers of fatalities due to head injuries which represent the cause of death in 69–93% of fatal accidents according to Oström *et al.* [9]. Therefore, wearing a helmet is of crucial and vital importance considering this high percentage of head trauma in cyclists.

G. Milne is PhD student in the biomechanic team at Strasbourg University in France, C. Deck, N. Bourdet and R. Willinger are respectively PhD researchers and Professor in the same team (caroline.deck@unistra.fr), Phone: +33.(0)3.68.85.29.40, Fax: +33(0)3.68.85.29.36. R.P. Carreira and Q. Allinne are respectively research and development laboratory manager and R&D engineer at Oxyane in Villeneuve d'Ascq (France)

The bicycle helmet protects the head against injury by reducing the impact energy that is transmitted to the head through energy absorption and dissipation through elastic and plastic deformation of its components (external shell and foam liner) and by increasing the area over which the impact is distributed. To be homologated and then sold, the helmet must pass a series of tests imposed by standards such as the EN 1078 in Europe [10]. This standard requires the helmet to be subjected to an energy absorption test consisting of linear impacts on both flat and kerbstone anvils at velocities of 5.42 m/s and 4.57 m/s respectively. For each impact, the helmet is fitted to a rigid ISO headform complying with the EN 960 requirements [11]. Linear accelerations along the three axes are recorded at the centre of gravity of the headform at the time of impact and the computed peak resultant linear acceleration must not exceed 250 g.

The present study aims at assessing a commercial bicycle helmet under normative impacts by means of both experimental and numerical methods. The literature reports a number of bicycle helmet models such as Willinger *et al.* in 1998 [12], Gilchrist & Mills in 2008 [13] and Asiminei *et al.* in 2009 [14]. None of them however provided a detailed validation against a number of impact points. Moreover, none of them were coupled to a human head FE model for a detailed head injury risk assessment against different injury mechanisms. In this context, the present paper reports a bicycle helmet modeling effort followed by a detailed validation against 90 experimental impact tests. Once validated, the helmet model has been coupled to an existing human head model (the Strasbourg University Finite Element model or SUFEHM) in order to compute the intra-cranial field parameters such as brain pressure, Von Mises stress and global energy of the CSF under normative test conditions. This step resulted in an original head injury risk assessment and an evaluation of the degree of protection offered by such a commercial bicycle helmet.

II. METHODS

Experimental Approach

As a first step and in accordance with the EN 1078 standard, an experimental program was carried out to perform impacts on a commercial bicycle helmet illustrated in Fig. 1. An moulded fabrication process allowed the external polycarbonate (PC) shell to be glued to an expanded polystyrene (EPS) foam liner of density 77 kg/m³. The shapes are sharp and numerous vent holes are designed leading to a total mass of 0.235 kg.



Fig. 1. Lateral view of the helmet

To assess the dynamic energy absorption characteristics of such a helmet in case of impact, an automatic electro-pneumatic shock absorption test equipment with a falling speed up to 8 m/s was used. This monorail experimental device complying with the EN 1078 is presented in Fig. 2a. The helmet was positioned on an instrumented magnesium alloy complete headform (Fig. 2b) in compliance with the EN 960 standard and the retention strap was tightly clamped to maintain the coupled head-helmet system during the test. A PCB 353/B17-3D triaxial accelerometer placed at the centre of gravity of the headform allowed the capture of the linear accelerations along the three axes for values up to 500 g. The sensor was linked to an ISO 6487 [15] certified TDAS PRO LAB data recorder equipped with a 250 kHz Sensor Input Module (SIM) card. The TDAS Control software installed on the computer provided tools for performing data collection and display.

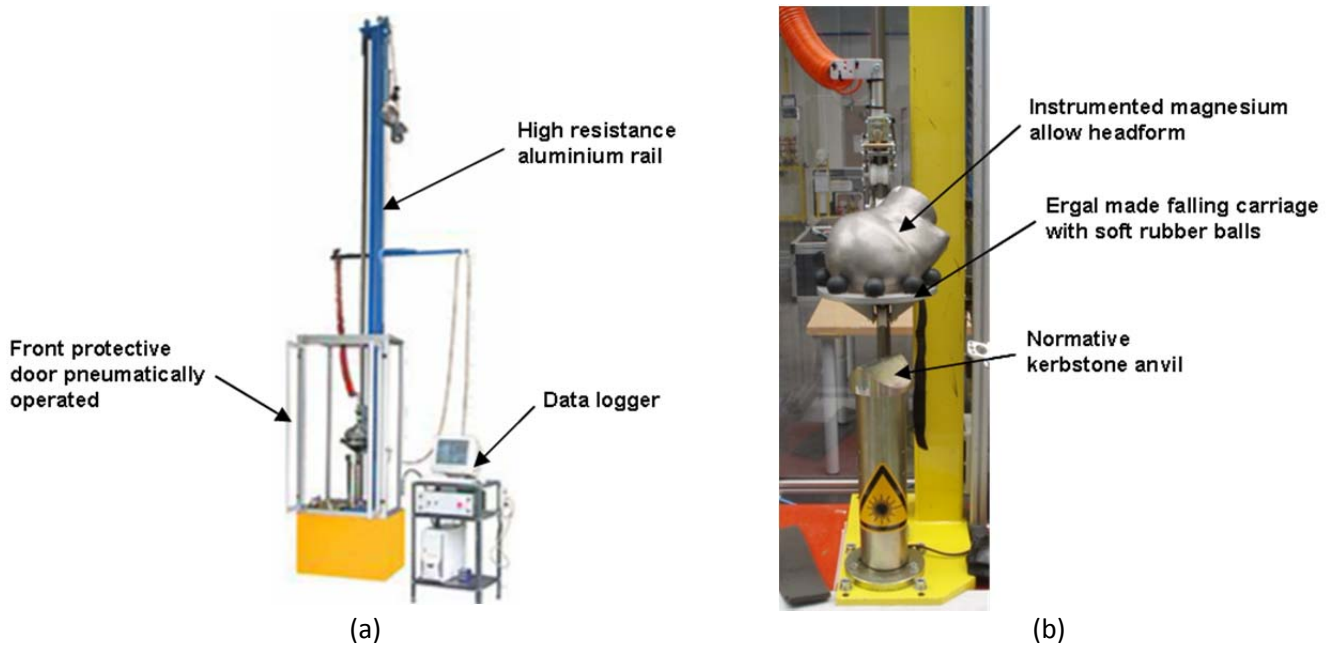


Fig. 2. Test apparatus used to perform experimental impact tests: (a) Monorail shock absorption test equipment (overall dimensions including base: mm. 860x800x5500), (b) Magnesium alloy complete headform

The resultant linear acceleration versus time curve was calculated according to equation (1) and filtered by a CFC filter with a 1 kHz cutoff frequency.

$$\gamma(t) = \sqrt{\gamma_x^2(t) + \gamma_y^2(t) + \gamma_z^2(t)} \tag{1}$$

where $\gamma(t)$ is the resultant linear acceleration (g), $\gamma_x(t)$ is the linear acceleration in x-axes (g), $\gamma_y(t)$ is the linear acceleration in y-axes (g) and $\gamma_z(t)$ is the linear acceleration in z-axes (g)

A total of 15 locations were impacted on both flat anvil (points A to O) and kerbstone anvil (points 1 to 15) at velocities of 5.42 m/s and 4.57 m/s respectively. Impact sites on flat anvil are shown by an X as illustrated in Fig. 3a-c. The 15 other points on kerbstone anvil are represented by a line drawn on the surface of the helmet (Fig. 3d-f). To ensure an accurate impact localisation, a laser pointer placed inside the anvil holder was used for tracking target points.

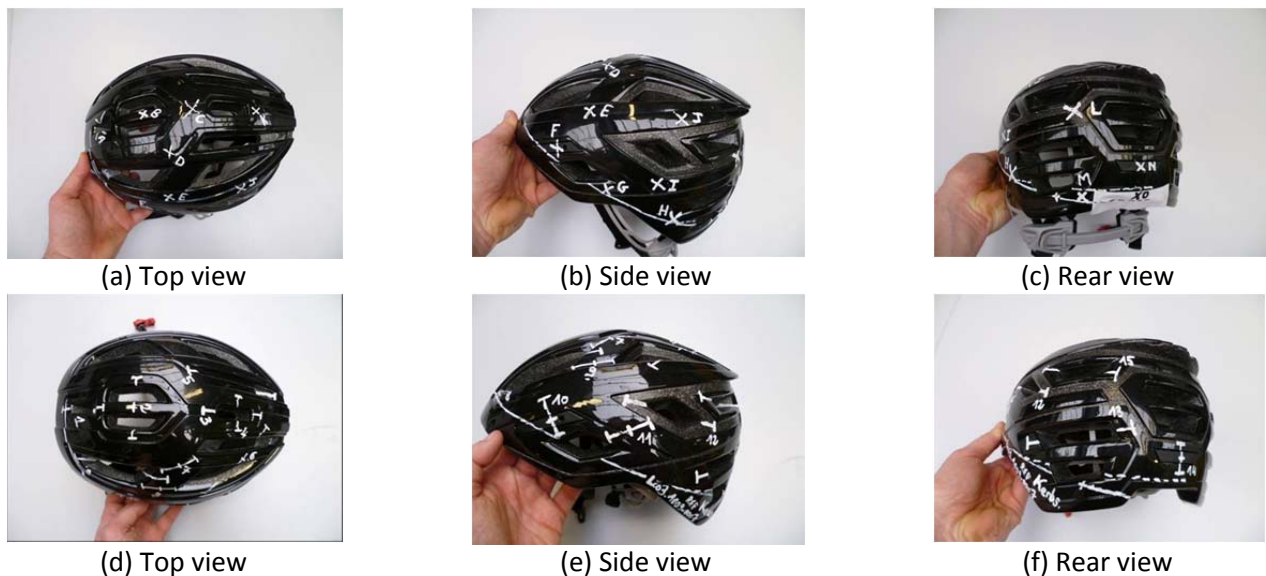


Fig. 3. Illustration of the impact points on the helmet during the experimental helmet test campaign

Before the impacts were performed, each of the 45 helmets were conditioned under one of the three following environmental conditionings:

- (-20 ± 2) °C in a BINDER 240L freezer for 4h to 6h
- (+50 ± 2) °C in BINDER M400 incubator for 4h to 6h
- Wet condition at ambient temperature: the helmet is placed under a shower for 4h to 6h

To comply with the EN 1078 requirements, all locations around the helmet were impacted under cold, hot and wet conditions so that a total number of 90 normative impact tests were performed experimentally.

Computational Modeling

The helmet under study was digitalized to get a Computer-Aided Design (CAD) of its geometry. The developed helmet model consists of two parts i.e. an external shell and a liner. The CAD was automatically meshed under the PAMCRASH® Mesh module. 4535 2D trias elements were created for the shell and 24380 3D tetras elements for the lining. Hence, the complete helmet FEM consists of 28915 elements. The whole model is presented in Fig. 4. Shell elements have a minimum and maximum size of 2.35 mm and 7.5 mm respectively. Concerning brick elements, the minimum element size is 2 mm. Finally, the meshing was generated to ensure a mesh continuity between the external shell and the liner.

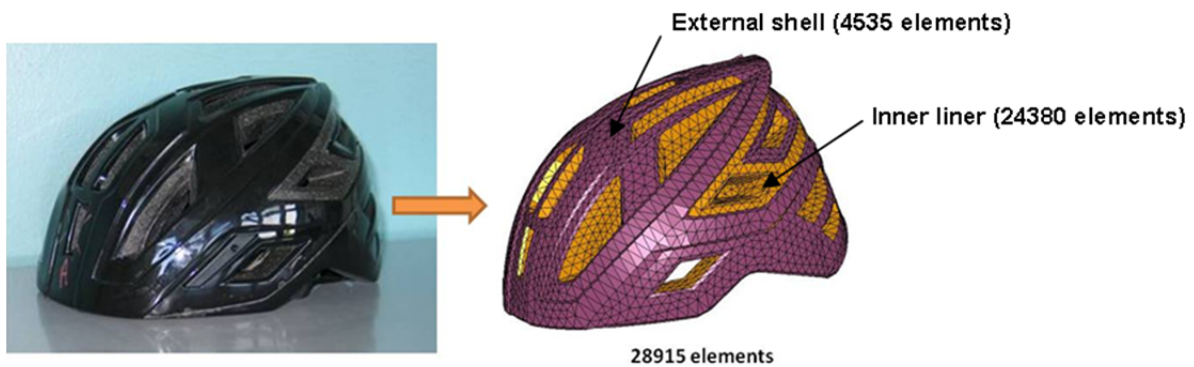


Fig. 4. General view of the bicycle helmet finite-element model

The mesh was imported under the LS-DYNA® explicit crash code and the material properties of the two helmet model’s parts were implemented. It was observed that under impact, the compressed EPS foam liner produces large deformations. In order to simulate such deformations, the EPS behavior was modeled by a tabulated "MAT_CRUSHABLE_FOAM" material law. The material properties implemented in the model were based on EPS sample tests and summarized in table 1. The plastic behavior of the EPS was modeled by a unique stress versus strain curve according to environmental conditions and corresponding to a dynamic loading of the material (Fig. 5). It can be observed that at low temperature, the material is stiffer than at high temperature or under wet condition. The Poisson’s coefficient of the foam was set close to zero due to its very high compressibility. The slope of the unloading curve was set to 28 MPa accordingly to Tinard *et al.* [16].

Table 1. Mechanical properties of the EPS foam

ρ (kg/m ³)	61.6
$E_{unloading}$ (MPa)	28
ν (-)	0.01

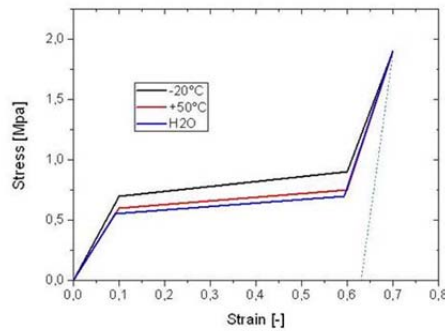


Fig. 5. Tabulated curves implemented in the material law

A linear elastic behavior was selected for the polycarbonate (PC) shell and modeled by the “MAT_ELASTIC” law. The values of the three parameters needed to characterize the PC material were extracted from the literature [17] and are reported in table 2. A measured thickness value of 1.18 mm was attributed to all shell elements.

Table 2. Mechanical properties of the PC shell

ρ (kg/m ³)	1055
E (MPa)	15000
ν (-)	0.42

To reproduce the 90 normative experimental tests, an ISO headform FEM was imported under the LS-DYNA® environment. This 5.7 kg headform was meshed with 3280 quadrilateral 4-nodes shell elements as shown in Fig. 6. The rigid behavior of its constitutive material was defined by the “MAT_RIGID” law with Poisson’s coefficient and Young’s modulus set to 0.2 and 200 GPa respectively.

The head-helmet contact of the coupled system illustrated in Fig. 6 was defined by taking into account a “CONTACT_AUTOMATIC_SURFACE_TO_SURFACE” interface with a 0.2 friction coefficient.

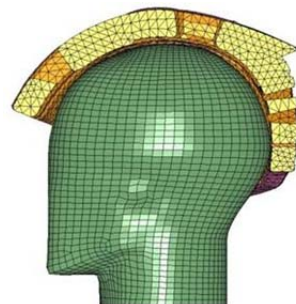


Fig. 6. Illustration of the headform model coupled to the bicycle helmet model

Two anvil models, flat (306 brick elements) and kerbstone (2820 brick elements), were created to perform the numerical impacts on both surfaces according to the experimental approach, as it can be observed in Fig. 7. The geometry and the dimensions of the flat anvil comply with the EN 1078 prescriptions (minimum diameter of (125 ± 3) mm and 24 mm thick), as do the kerbstone anvil (angle of $90 \pm 0.5^\circ$, 50 mm minimum height and 200 mm minimum length). The “MAT_ELASTIC” material law and the parameter values as mentioned in table 3 are the same for both impacted surfaces. A “CONTACT_AUTOMATIC_NODE_TO_SURFACE” interface with a friction coefficient of 0.1 was defined to compute the shocks on the two anvils.

Table 3. Mechanical properties of the flat/kerbstone anvil

ρ (kg/m ³)	7800
E (MPa)	200000
ν (-)	0.3



Fig. 7. Illustration of the simulation of standard impact tests against two anvils: (a) Flat anvil, (b) Kerbstone anvil

In order to assess the risk of head trauma in terms of diffuse axonal injury (DAI) and subdural hematoma (SDH) under normative impacts, a coupling between the bicycle helmet FEM and the Strasbourg University Finite Element Model (SUFEHM) was performed under the LS-DYNA® software. This model developed by Kang *et al.* in 1998 [18] and illustrated in Fig. 8 was meshed with 10395 brick elements and 2813 shell elements. Based on anatomical atlas, the head model contains the face, scalp, skull and a homogenous brain. Intra-cranial membranes and cerebrospinal fluid (CSF) are also represented in this model. The constitutive material laws of the different parts of the model have been defined by the material laws specified in appendix 1 according to Willinger *et al.* (1998) [19]. This model was validated under dynamic experimental tests reported by Nahum *et al.* (1977) [20], Trosseille *et al.* (1992) [21] and Yoganandan *et al.* (1994) [22]. This head model has been extensively used for the simulation of a number of well documented real world head trauma in order to correlate intra-cranial mechanical parameters with the occurrence of injury. This approach permitted us to define model based head injury criteria reported by Deck *et al.* in 2008 [23], as follows:

- 50% risk of moderate neurological injury (DAI1+): Brain Von Mises shearing stress of 28 kPa
- 50% risk of severe neurological injury (DAI2+): Brain Von Mises shearing stress of 53 kPa
- 50% risk of subdural hematoma: CSF strain energy of 4950 mJ

The interface between the energy absorbing foam and the human head model (Fig. 9a) was computed by an "AUTOMATIC_NODE_TO_SURFACE" LS-DYNA® contact with a friction coefficient set to 0.2. An example of positioning of the coupled head-helmet system for a lateral impact on a flat anvil is shown in Fig. 9b.

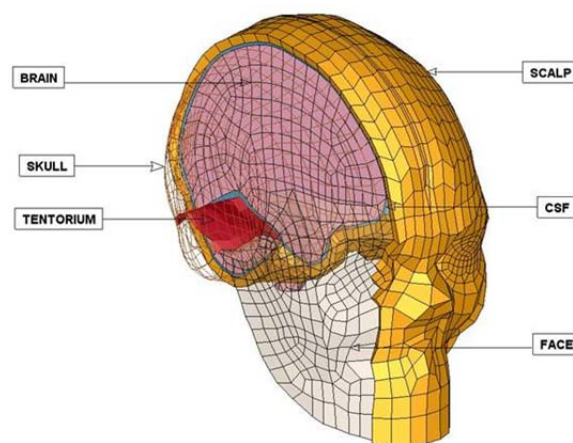


Fig. 8. Strasbourg University Finite Element Head Model

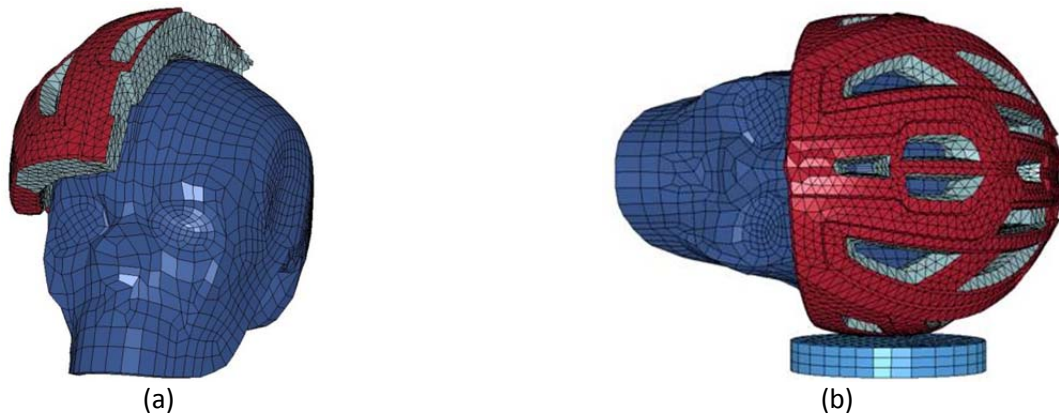


Fig. 9. Helmet-SUFEHM coupling: (a) Illustration of the head-helmet interface, (b) Positioning of the coupled system for a normative impact on flat anvil

III. RESULTS

During the validation process, each of the 30 helmet target points was impacted experimentally and numerically under three environmental conditionings (-20°C, +50°C and humidity). The numerical resultant linear acceleration was computed at the centre of gravity of the headform in order to superimpose it with the experimental result. In the framework of this in-depth helmet validation effort, results in terms of resultant linear acceleration versus time curve were superimposed with experimental results as well as the peak values. An illustration is given for a crown impact (point C) at 5.42 m/s on a flat anvil under low temperature, high temperature and under humidity treatment in Fig. 10. A good agreement is observed in terms of time duration (8 ms) and peak resultant linear acceleration demonstrating that the stress-strain curve defined for each condition is well suited to the energy absorbing material in the considered loading case. Numerical peak g is 163 g, 166 g and 174 g under -20°C, +50°C and H2O condition respectively. Related experimental values are 169 g, 161 g and 165 g leading to 3.7%, 3.0% and 5.2% relative errors.

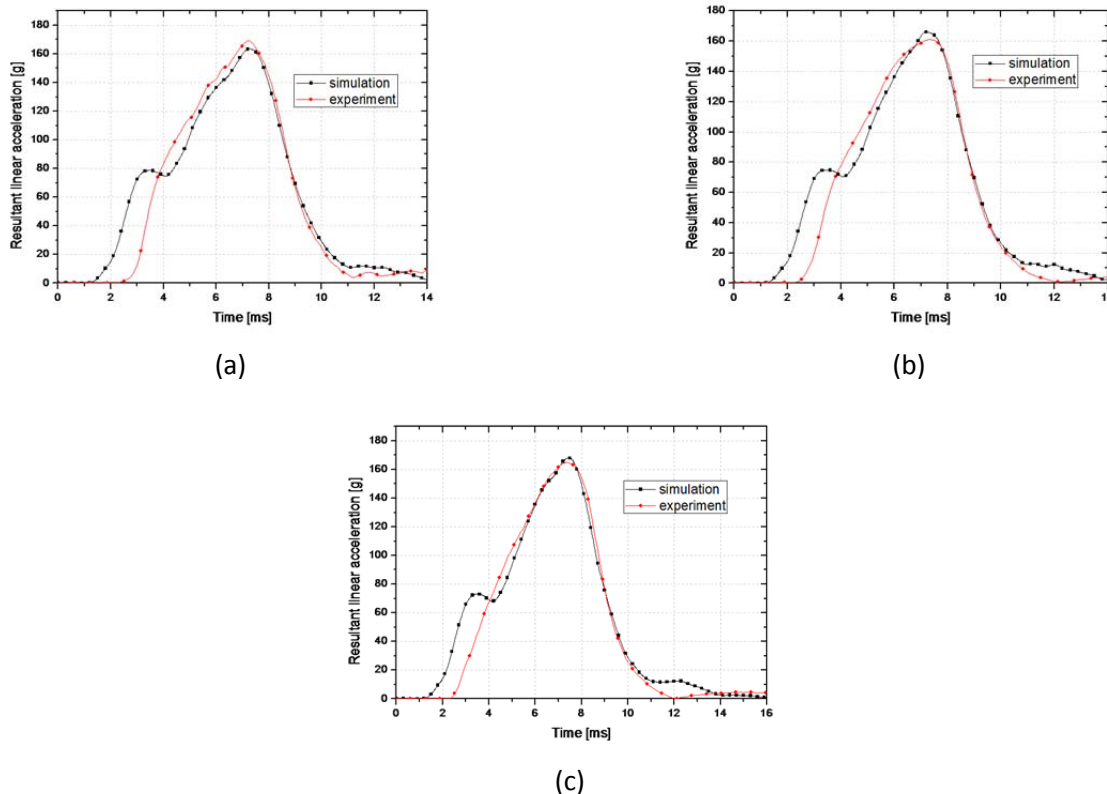


Fig. 10. Superposition of experimental and numerical headform acceleration under crown impact at 5.42 m/s against a flat anvil: (a) Cold condition, (b) Hot condition, (c) Wet condition

Time history resultant linear accelerations obtained for a frontal impact (point 1) on kerbstone anvil are shown in Fig. 11 under cold, hot and humid conditionings. By analyzing the time durations (12 ms) and peak values between numerical and experimental results, a good agreement is also observed. Numerical simulation of impacts tests led to peak values of 76 g at -20°C, 88 g at +50°C, 83 g under humidity condition. Compared to experimental values, relative errors are respectively 5.3%, 13.6% and 2.4%.

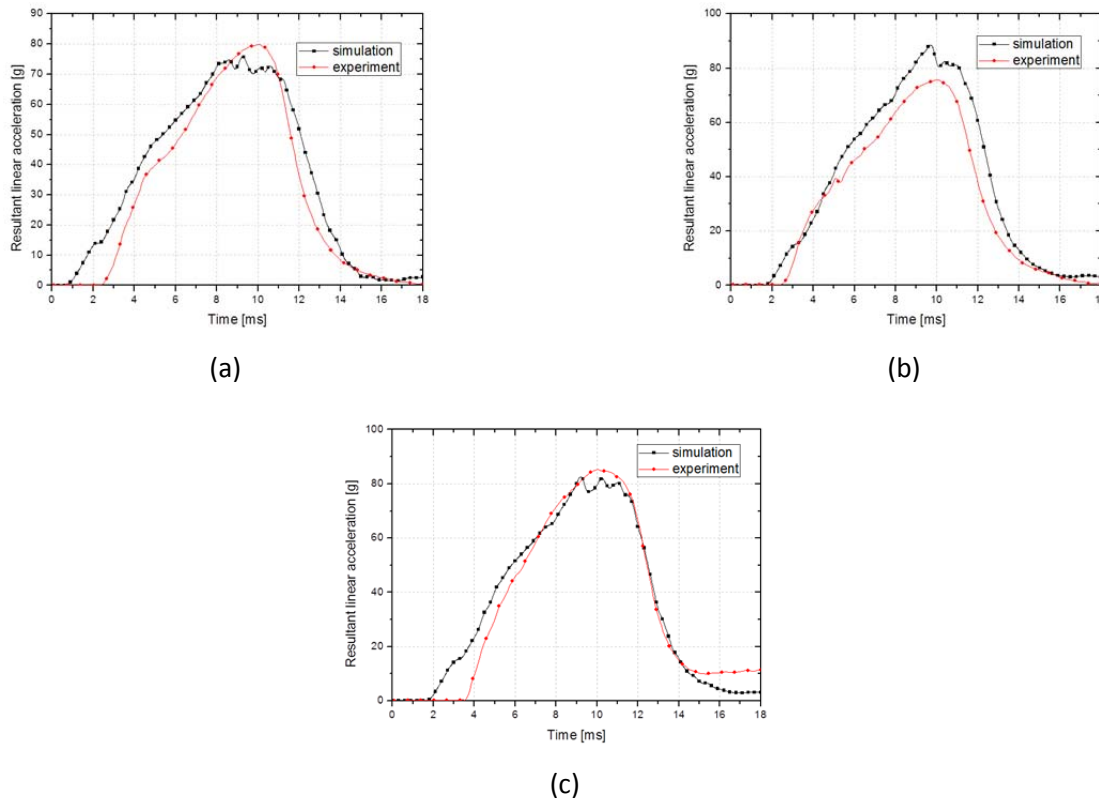
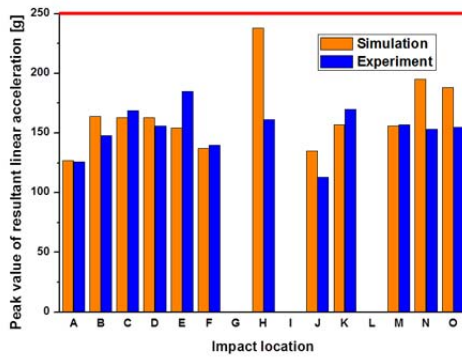
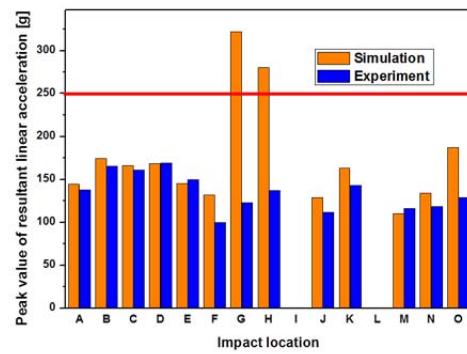


Fig. 11. Superposition of experimental and numerical headform acceleration under frontal impact at 4.57 m/s against a kerbstone anvil: (a) Cold condition, (b) Hot condition, (c) Wet condition

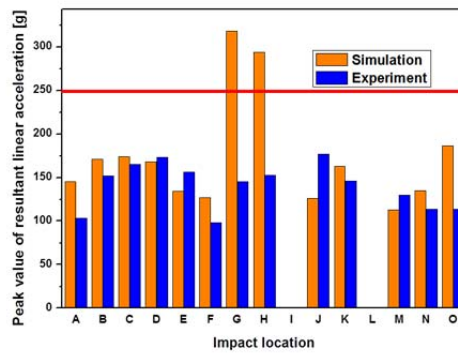
Results for 38 impact configurations obtained by impacting the helmet on a flat anvil are shown in Fig. 12 for the experimental and numerical approach. The validity of all simulations has been checked by comparing both hourglass and total energy of the system. To do so, the hourglass energy that is a numerical energy reflecting calculation errors must be lower than 10% of the total energy. In terms of peak resultant linear acceleration, a good agreement is particularly seen for points A to F under each of the three conditionings. Nonetheless, the theoretical acceleration is overestimated for points G and H. This artefact can be explained by the extreme sensitivity of the model response to the positioning of the helmet towards the anvil. Another reason which can explain these differences in peak values is that rupture and high shear deformations of the EPS liner appear when impacting these critical points, phenomena which are not taken into account in the present material model. Missing points (I and L) are points for which numerical instabilities have been observed and for similar reasons.



(a)



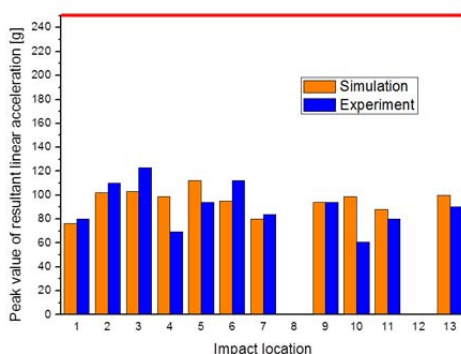
(b)



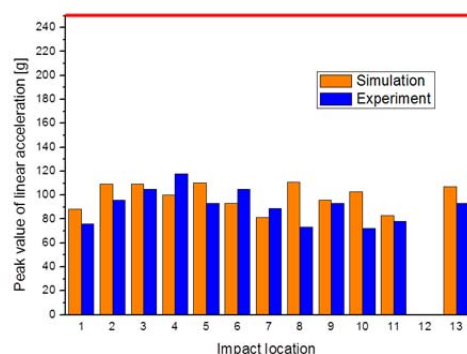
(c)

Fig. 12. Comparison of experimental and computed maximum headform acceleration under impacts against the flat anvil: (a) Cold condition, (b) Hot condition, (C) Wet condition

A comparison between experimental and numerical peak acceleration values for impacts on kerbstone anvil at 4.57 m/s velocity and under all conditionings is presented in Fig. 13-14. For the 35 impact configurations, results show a good agreement between experimental and numerical data. Missing points, respectively points 12, 14 and 15 under all environmental conditions, led to numerical instabilities and hourglass energies higher than 10% of the total energies probably due to rupture as pointed out previously. It should be mentioned that for all impacts, the peak resultant linear acceleration never exceeded the EN 1078 acceleration limit fixed at 250 g.



(a)



(b)

Fig. 13. Comparison of experimental and computed maximum headform acceleration under impacts against the kerbstone anvil: (a) Cold condition, (b) Hot condition

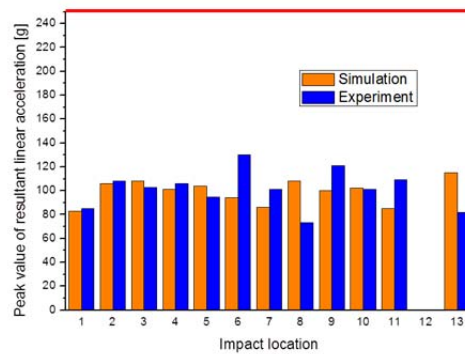


Fig. 14. Comparison of experimental and computed maximum headform acceleration under impacts against the kerbstone anvil under wet condition

When coupled to the human head model, intra-cranial parameters have been computed in order to assess the injury risks in terms of diffuse axonal injury and subdural hematoma under normative impacts in accordance with the model based injury criteria presented in the Methods section.

As for the numerical simulations with the headform model, the validity of each simulation has been verified by comparing both hourglass and total energy of the system. Still, hourglass energy must be lower than 10% of the total energy involved.

The peaks Von Mises intra-cerebral stress computed under impact on both flat and kerbstone anvils for all target points and under the three normative conditionings are shown in Fig. 15. Generally speaking, most of the impact points led to significant but acceptable brain shearing. For normative impacts on kerbstone anvil, Fig. 15b also shows that the Von Mises stress calculated for each impact is lower than 28 kPa leading to a percentage of moderate DAI risk less than 50% for all impact configurations. Injury assessment in terms of percentage of risk to sustain a moderate DAI for the helmeted head impacting a flat or a kerbstone anvil are presented respectively in appendix 2 and appendix 3.

Results obtained in terms of internal strain energy within the CSF layer for impacts on flat and kerbstone anvils, both under the three environmental conditionings, are presented in Fig. 16. Risks for the helmeted user to suffer from a SDH in terms of percentage of risk after impacting a flat surface under normative impact conditions are mentioned in appendix 4. As demonstrated in Fig. 16b, impacts realized on kerbstone anvil led to injury risk far below 50%, with a maximum risk of SDH of 5% obtained by impacting the point 2 under cold conditioning as it appears in appendix 5.

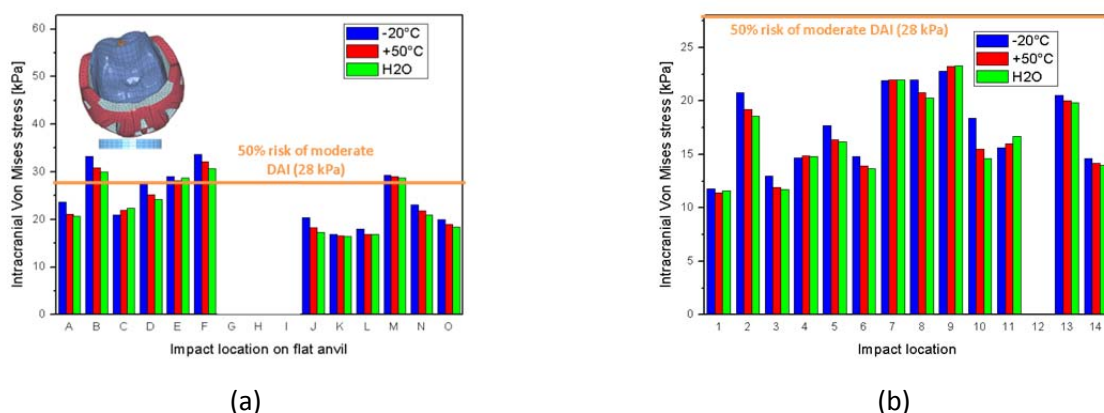


Fig. 15. Peak intra-cerebral shearing stress computed with the helmet model coupled to the human head model for all impact points: (a) Flat anvil, (b) Kerbstone anvil

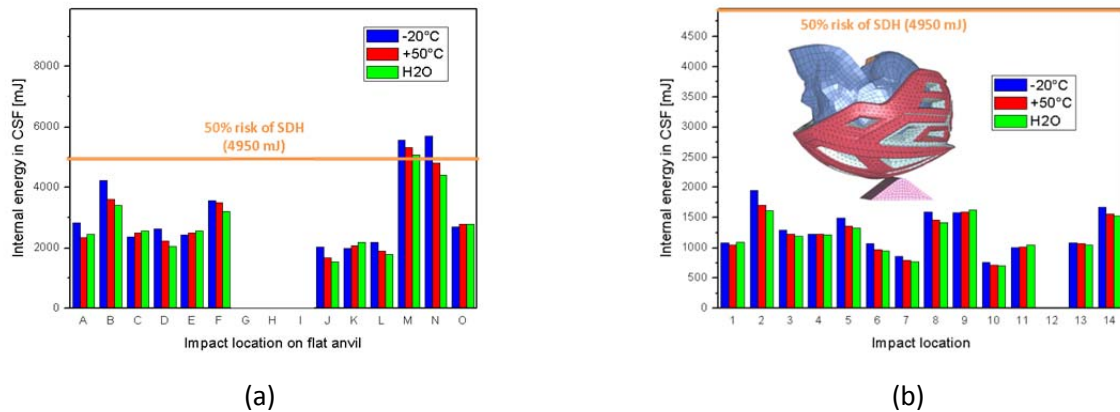


Fig. 16. Peak CSF strain energy computed with the helmet model coupled to the human head model for all impact points: (a) Flat anvil, (b) Kerbstone anvil

IV. DISCUSSION

This paper proposes a detailed FE model of an existing commercial bicycle helmet. Based on strict requirements imposed by the EN 1078 standard, numerical simulations were performed and a comparison against 90 experimental impact tests in terms of peak resultant linear acceleration was carried out in order to validate the helmet model under three conditionings and against flat and kerbstone anvils. Even though a number of bicycle helmet models are reported in the literature, such an in-depth validation has never been undertaken to the authors' knowledge.

For most of the impact points, whether on flat or kerbstone anvil, a very good agreement has been shown with relative errors remaining under 10%. Such results are typically obtained for frontal and crown impacts. However, it must be mentioned that for a limited number of points such as points G, H and M mainly located in lateral or occipital regions, relative errors are less acceptable. The reason of this situation may be due to a very high sensitivity of the headform response to the position of the impact site on the helmet and the direction of the impact as non controlled rotation may be introduced. Another possible reason for errors between experiment and simulation for such critical impact points is that under lateral impact, the helmet presents cracks due to an extreme material loading, a phenomenon which is not taken into consideration in the current material constitutive law.

As LS-DYNA® material law implemented in the model to reproduce the compression of the foam liner does not take into account any shear deformations or cracks of the EPS, further improvement of the EPS material law is needed in order to progress towards a more realistic helmet model under lateral impact.

Even if current bicycle helmets are designed to reduce headform acceleration, they are still not optimized to reduce human head injuries. In order to progress towards this final objective, head injury risk assessment under standard impact conditions was undertaken in this study. It appears that, for the validated impact points, the head injury risk is quite limited. It should be mentioned that the risk of skull fracture was not considered in the present study and that a few lateral impact points clearly need further investigations.

The head injury risks have been investigated only in case of normal impacts but accident analysis shows [24] that most of the bicycle helmet impacts are oblique, with the most common impact sites located at the front and sides of the helmet [25] causing both linear and rotational accelerations to the head. In bicycle helmet test standards, test impacts are perpendicular to the surface of fixed anvils, and the peak headform linear acceleration is used as a pass/fail criterion. Helmet standards currently in use today do not measure any rotational effects to the headform. However, rotational head acceleration results in large shear strains arising in the brain, a phenomenon which should be taken into account in further helmet investigations by developing a validated helmet model against experimental oblique impact tests in terms of both peak linear and rotational accelerations. A number of technological solutions already exist (crushing material or structural decoupling) in order to reduce head rotational acceleration. Coupling this potential validated model to the anatomic head, it would then be possible to optimize the helmet against life-threatening rotational effects to the brain.

V. CONCLUSIONS

In this study, a finite-element model of a brand new bicycle helmet was developed, implemented and validated under the LS-DYNA® explicit crash code.

The numerical simulation of 90 experimental normative impact tests, under three environmental conditionings and two anvils, was performed by coupling the helmet FEM to a rigid 5.7 kg ISO headform complying with the EN 960 standard. Results in terms of headform acceleration time-history and peak g values between experiment and simulation are in good agreement for most of the impact points thus validating the helmet model. However, for impact points located laterally and close to the helmet edge, further improvement of the helmet model is needed.

Once validated, this helmet FE model was coupled to the Strasbourg University FE Head Model in order to assess the head injury risks of both DAI and SDH injuries. Results show that normative impacts on flat anvil are more critical than impacts against kerbstone anvil. Results also show that the computed injury risk is acceptable for most of the impact points. This work is therefore a step towards both helmet optimisation against biomechanical head injury criteria and the consideration of model based head injury criteria into future helmet standards.

VI. ACKNOWLEDGEMENT

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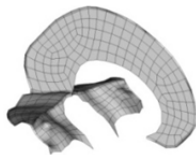
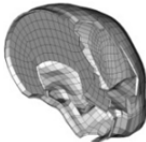
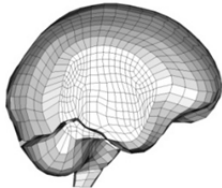
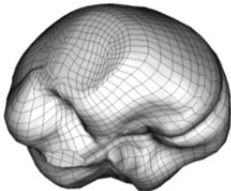
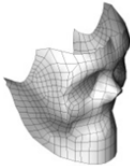
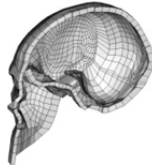
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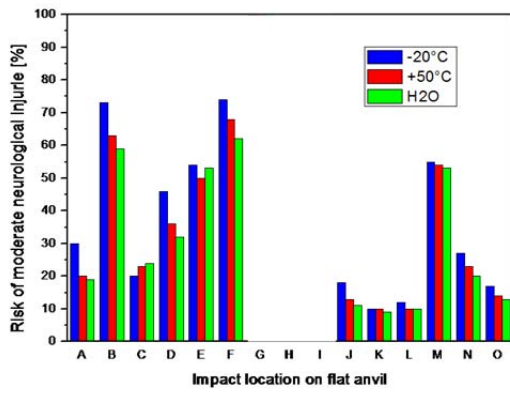
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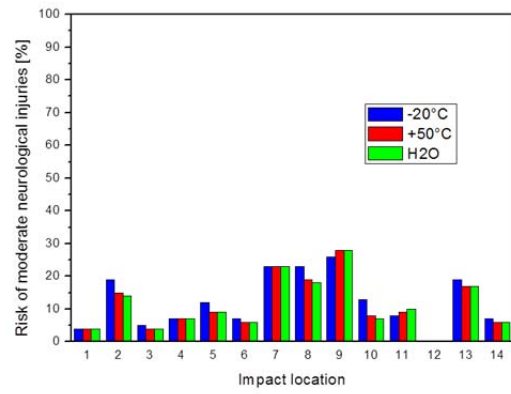
VIII. APPENDIX

APPENDIX 1. MECHANICAL PROPERTIES OF THE SUFEHM CONSTITUTIVE PARTS

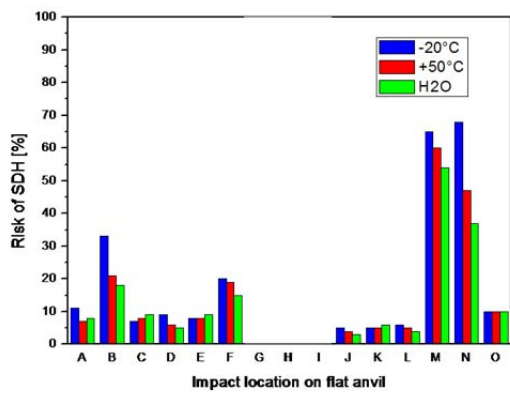
Segment	Illustration	Mechanical behavior	Mechanical parameters	Mechanical parameters
Falx and Tent		Linear elastic	$e = 1 \text{ mm}$ $\rho = 1140 \text{ kg/m}^3$ $E = 31.5 \text{ MPa}$ $\nu = 0.45$	/
Brain-Skull interface		Linear elastic	$\rho = 1040 \text{ kg/m}^3$ $E = 0.012 \text{ MPa}$ $\nu = 0.49$	/
Brain and Cerebellum		Viscous elastic	$\rho = 1040 \text{ kg/m}^3$ $K = 1125 \text{ MPa}$ $G_0 = 0.049 \text{ MPa}$ $G_{inf} = 0.0167$ $\beta = 145 \text{ s}^{-1}$	/
Skull		Fragile elastic-plastic	Cortical	Spongy
			$e = 2 \text{ mm}$ $\rho = 1900 \text{ kg/m}^3$ $E = 15000 \text{ MPa}$ $\nu = 0.21$ $K = 6200 \text{ MPa}$ $UTS = 90 \text{ MPa}$ $UTC = 145 \text{ MPa}$	$e = 3 \text{ mm}$ $\rho = 1500 \text{ kg/m}^3$ $E = 4600 \text{ MPa}$ $\nu = 0.05$ $K = 2300 \text{ MPa}$ $UTS = 35 \text{ MPa}$ $UTC = 28 \text{ MPa}$
Face		Linear elastic	$e = 10 \text{ mm}$ $\rho = 2500 \text{ kg/m}^3$ $E = 5000 \text{ MPa}$ $\nu = 0.23$	/
Skin		Linear elastic	$\rho = 1000 \text{ kg/m}^3$ $E = 16.7 \text{ MPa}$ $\nu = 0.42$	/



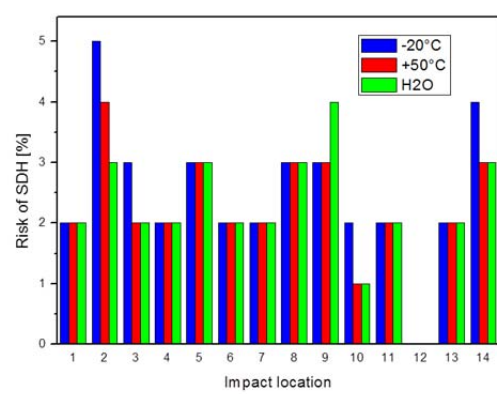
APPENDIX 2. Risk of moderate DAI for all impact points on flat anvil and under three conditionings



APPENDIX 3. Risk of DAI for 12 impact points on kerbstone anvil and under three conditionings



APPENDIX 4. Risk of SDH for all impact points on flat anvil and under three conditionings



APPENDIX 5. Risk of SDH for 12 impact points on kerbstone anvil and under three conditionings